

# Lifting between the set of three way contingency tables and r-neighbourhood theorem

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## 1 Lifting by Sasaki's Criation Operator for two way tables

Here we briefly review on creation operators for two way contingency tables. Let  $\Omega(\alpha, \beta)$  be the set of all tables with a row sum vector  $\alpha$  and a column sum vector  $\beta$ . In the sequential conditional test, whenever a new sample is added in  $(p, q)$  cell the basic space of inference changes to  $\Omega(\alpha + e_p, \beta + e_q)$  where  $e_j$  denotes the  $j$ -th canonncal unit vector. We want to generate  $\Omega(\alpha + e_p, \beta + e_q)$  from  $\Omega(\alpha, \beta)$  where the latter is already in hand. Let  $\Phi(\alpha, \beta)$  be a characteristic function of the set  $\Omega(\alpha, \beta)$ , that is,

$$\Phi(x|\alpha, \beta) = \sum_{H \in \Omega(\alpha, \beta)} \frac{x^a}{a!},$$

where  $H = (a_{ij})$  and  $x = (x_{ij})$ , and  $x^a = \prod x_{ij}^{a_{ij}}$  and  $a! = \prod_{ij} a_{ij}!$ . Sasaki operators are defined by

$$S_{pq} = x_{pq} + \sum_{i,j} x_{iq} x_{pj} \frac{\partial}{\partial x_{ij}}$$

Then we have the next proposition,

**Proposition(Sasaki(1991))**

$$S_{pq}\Phi(x|\alpha, \beta) = (1 + \alpha_p)(1 + \beta_q)\Phi(x|\alpha + e_p, \beta + e_q).$$

Our new view of Sasaki operator for  $K \times L$  tables is that  $S_{pq}$  can be viewed as a set of mappings  $\{\delta_{pq}, \phi_{pq}^{ij}, i = 1, 2, \dots, K \text{ and } j = 1, \dots, L\}$  where  $\delta_{pq}$  denotes a mapping that maps  $H$  in  $\Omega(\alpha, \beta)$  to  $\overline{H} = H + {}^t e_p e_q$  in  $\Omega(\alpha + e_p, \beta + e_q)$  and  $\phi_{pq}^{ij}$  denotes a mapping that maps  $H$  into  $\overline{H} = H + {}^t e_i e_q + {}^t e_p e_j - {}^t e_p e_q$ . Then the above proposition restated that the set of mappings  $\mathcal{S} = \{\delta_{11}, \phi_{pq}^{ij}, i = 1, \dots, K \text{ and } j = 1, \dots, L\}$  constitutes a surjective set of mappings from  $\Omega(\alpha, \beta)$  to  $\Omega(\alpha + e_p, \beta + e_q)$ . Here it should be noted that the term "surjectivity" is used for some unusual sense. In this paper we call a set  $\mathcal{S}$  of mappings, from  $\mathcal{X}$  to  $\mathcal{Y}$ , "surjective" if for any  $y \in \mathcal{Y}$  there is some  $x \in \mathcal{X}$  and  $f \in \mathcal{S}$  such that  $y = f(x)$ . Further, it is very interesting that Sasaki operator was devised as creation operator of an  $A$ -hyperbolic partial differential system and it was first recognized as a creation operator for two way contingency tables in Saito et. al(1997). Sakata and Sawae(2003) used this creation operator in the sequential conditional test and studied the performance of the test.

## 2 Lifting Operator for Three Way Tables

In this section we consider how to construct a lifting operator for three way contingency tables. Let  $\Omega(\alpha, \beta, \gamma)$  be the set of all tables with a fixed  $x - y, y - z$  and  $x - z$  marginal two way tables,  $\alpha, \beta$  and  $\gamma$  respectively. In the sequential conditional test, whenever a new sample is added in  $(p, q, r)$  cell the basic space of inference changes from  $\Omega(\alpha, \beta, \gamma)$  to  $\Omega(\alpha + E_{pq}, \beta + E_{qr}, \gamma + E_{pr})$  where  $E_{ij}$  denotes the two way table with 1 in  $(i, j)$  cell and 0 in all other cells. We want to generate  $\Omega(\alpha + E_{pq}, \beta + E_{qr}, \gamma + E_{pr})$  from  $\Omega(\alpha, \beta, \gamma)$  where the latter is already in hand. That is, we want to obtain  $\mathcal{S}$ , a set of mappings from  $\Omega(\alpha, \beta, \gamma)$  to  $\Omega(\alpha + E_{pq}, \beta + E_{qr}, \gamma + E_{pr})$ , which is "surjective" in the sense of Section 2 and algorithmically easily implementable. Here we propose a conjecture about a surjective set of mappings. For stating our conjecture, to avoid complexity of suffix, we confine ourselves to the case of  $(p, q, r) = (1, 1, 1)$  without loss of generality. We use this notation throughout this paper from here.

The following Theorem 1 is obvious and given without proof, but becomes a powerful tool to prove partially the conjecture in the later section.

**Theorem(Ishii and Sakata)** All elements  $\bar{H}$  with  $\bar{H}(1, 1, 1) \geq 1$  in  $\Omega(\alpha + E_{11}, \beta + E_{11}, \gamma + E_{11})$  is obtainable by some  $H$  in  $\Omega(\alpha, \beta, \gamma)$  by simply applying  $\delta_{111}$  to  $H$ . Let  $\mathcal{M}$  be the set of minimal Markov basis and let  $\mathcal{M}^k$  be the subset of  $\mathcal{M}$  consisting of all Markov moves  $M$  with  $M_{111} = k$ . The following Theorem is one of our target theorems to prove.

**Theorem A** Assume we have a set of a minimal Markov basis of moves. Let  $\phi = \{\delta_{i,j,k}, M_1^0 + M_2^0 + M_3^1\}$  where  $M_1^0$  and  $M_2^0$  are minimal Markov moves with  $x_{ijk} = 0$  and  $M_3^1$  is a Markov move with  $x_{ijk} = 1$ . Then  $\phi$  is a surjective from  $\Omega(\alpha, \beta, \gamma)$  to  $\Omega(\alpha + \delta_{ij}, \beta + \delta_{jk}, \gamma + \delta_{ik})$  for any  $\alpha, \beta$ , and  $\gamma$  for  $3 \times 3 \times 3$  contingency tables.

Let  $\mathcal{M}$  be the set of minimal Markov basis. We introduce a  $r$ -neighbourhood property for  $\Omega(\alpha, \beta, \gamma)$ .

**Definition 2.1** Let  $H$  be an element  $\Omega(\alpha, \beta, \gamma)$ . An element  $H'$  in  $\Omega(\alpha, \beta, \gamma)$  is said to be in a  $r$ -neighbourhood of  $H$  if there is a path of Markov moves  $M_1, \dots, M_r$  of  $\mathcal{M}$  such that

$$H' = H + M_1 + \dots + M_r$$

where  $H_s = H + M_1 + \dots + M_s$  is non-negative for all  $s \leq r$ .

$\Omega(\alpha, \beta, \gamma)$  has  $r$ -neighbourhood property if any element  $H$  in  $\Omega(\alpha, \beta, \gamma)$  has an element  $H'$  with  $H'_{ijk} = 1$  within its  $r$ -neighbourhood. Then Theorem A can be express as

**Theorem A'** For  $3 \times 3 \times 3$  contingency tables,  $\Omega(\alpha + \delta_{ij}, \beta + \delta_{jk}, \gamma + \delta_{ik})$  has 2-neighbourhood property.

We have the following properties by computer programs.

**Theorem B**  $3 \times 3 \times 4$  contingency tables has 3-neighbourhood property. All proofs are omitted due to the lack of space.